Requirements brief:

* Be able to detect obstacles above and the surface level up to a range of 2 meters along the axis of vision.
* Should be able to communicate the type and proximity of the obstacle
* Should be able to detect when the change in g spikes (values to be determined)
* Be able to communicate the results as an emergency alert
* Should have access to cancel the emergency alert
* Should be able to communicate the location user
* Facial recognition for familiar faces